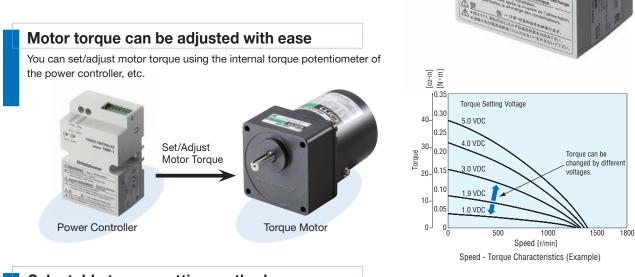
# **O**riental motor

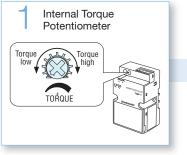
## (RoHS) RoHS-Compliant Power Controller for Torque Motors **TMP-1**

A new power controller developed for Oriental Motor's torque motors that allows for easy adjustment of torque. A perfect choice for winding applications, push-motion mechanisms and other situations where torque must be adjusted.

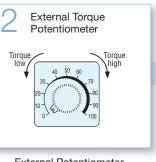


## Selectable torque setting method

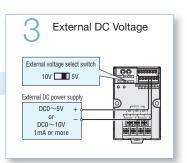
Torque can be set using one of three methods according to your needs. You can also change torque between two levels by switching between the internal potentiometer and an external potentiometer/voltage.



Built-In Potentiometer



External Potentiometer PAVR-20KZ (Sold Separately)

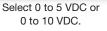


POWER CONTROLLER MODEL TMP-1

Orientalmotor

WARNING

AVERTISSEMENT



## **Full Range of Functions**

- Two torque levels can be set by the internal potentiometer and an external potentiometer/voltage
- •Alarm output function (detection of an open thermal protector)
- Instantaneous bi-directional operation by CW/CCW signal switching
   Switching of signal input logic between sink and source





**World K Series** Torque Motors 3 W (1/250 HP) - 20 W (1/38 HP)

## Specifications of Motor and Power Controller Combinations

• 3 W (1/250 HP), 6 W (1/125 HP), 10 W (1/75 HP), 20 W (1/38 HP) Rolls Motor: CAUs C C Power Controller: 🏨 C C

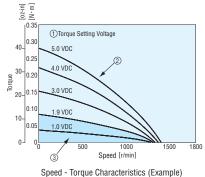
3	W (1/250 HP), 6 \	/v (1/125 Hi	P), IU W		, 20 VV	(1/38 H	P) (ROH		otor: c7		00	P0\	ver Cor	ntroller:	LISTED CC
	Motor Model	Rating at Locked Rotor	Voltage	Frequency	Torque Setting Voltage*	Starting	) Torque		Output wer	Speed at Max. Output Power	Torqu Max. C Pow	utput	Max. Input Current	Max. Input Power	Capacitor
	Pinion Shaft Type (Round Shaft Type)	LUCKED ROIOF	VAC	Hz	VDC	mN∙m	oz-in	W	HP	r/min	mN⋅m	oz-in	A	Power W	μF
_	(nound onart type)		110		VDO		02-111	vv					0.49	53	μι
	2TK3GN-AW2U	5 minutes	115	60	5.0	70	9.9	3.5	1/210	900	38	5.3	0.10	58	
TP	(2TK3A-AW2U)		110								13 1.84	0.31	22	- 6.0	
		Continuous	115	60	1.7	25	3.5	1.2	1/620	900		0.33	24		
			220					2.8	1/270		36	5.1	0.23	49	
			230	50	5.0	70	9.9	3	1/250	750	39	5.5	0.25	54	
		5 minutes	220		5.0	70		0.5	1/010	000			0.25	55	
TR	2TK3GN-CW2E		230	60	5.0	70	9.9	3.5	1/210	900	38	5.3	0.27	60	4.5
TP	(2TK3A-CW2E)		220	50		40	0.5		4/000	750	10	0.15	23	1.5	
		Continuous	230	50	2.2	18	2.5	0.8	1/930	750	10	1.42	0.16	26	
		Continuous	220	00	10	05	0.5	1.0	1/000	000	10	1.04	0.16	24	-
			230	60	1.6	25	3.5	1.2	1/620	900	13	1.84	0.17	27	
		5 minutes	110	60	5.0	150	21	8	1/93	900	87	0.7	0.72	78	9.0
TP	3TK6GN-AW2U	5 minutes	115	00	5.0	150	21	0	1/93	900	07	12.3	0.76	86	
UP	(3TK6A-AW2U)	Continuous	110	60	1.7	55	7.8	2.6	1/290	900	28 3.9	0.48	34	9.0	
		Continuous	115	00	1.7	55	7.0	2.0	1/230	500	20	0.0	0.50	37	
			220	50	5.0	140	19.8	6	1/125	750	78	78 11.0	0.40	81	2.5
		5 minutes	230		5.0	140	13.0	0	1/125	730	70		0.44	92	
		5 minutes	220	60	5.0	150	21	8	1/93	900	87	12.3	3 0.40 87	87	
	3TK6GN-CW2E (3TK6A-CW2E)		230		5.0	100	21	0	1/30	500	07	12.0	0.42		
			220	50	1.7	45	6.3	1.8	1/410	750	24	34	0.22	31	
		Continuous	230				0.0					0.1	0.23		
			220	60 1.	1.3	55	7.8	2.6	1/290	900	28	3.9	0.25	34	
			230					-			-		0.26 37		
P		5 minutes	110	60	5.0	210	29	12	1/62	900	130	18.4	0.91	99	- 11
	4TK10GN-AW2U (4TK10A-AW2U)		115										0.96	109	
		Continuous	110	60	1.5	70	9.9	3.3	1/230	900	35 4.9	0.55	37	-	
			115 220										0.59 42 0.47 100	<u> </u>	
		5 minutes	220	50	5.0	220	31	10	1/75	750	130 18	18.4	0.47	111	
	4TK10GN-CW2E (4TK10A-CW2E)		3 <u>230</u> 220									0.51	111	-	
			230	60	5.0	210	29	12	1/62	900	130	18.4	0.51	121	
TP			230										0.33	38	3.0
		Continuous	230	50	1.6	65	9.2	2.8	1/270	750	35 49	42	-		
			Continuous 220		1.3		70 9.9				35		0.23	43	-
				60		70		.9 3.3	3.3 1/230	1/230 900		4.9	0.33	47	
			110										1.22	134	
TP	5TK20GN-AW2U	5 minutes	115	60	5.0	350	) 49	23	23 1/32	1/32 900	250	35	1.29	147	- 14
	(5TK20A-AW2U)	1	110										0.76	51	
		Continuous —	115	60	1.4	100	14.2	5.5	1/140	900	60 85 -	0.79	55	1	
TR	5TK20GN-CW2E (5TK20A-CW2E)		220	50	5.0	050	40		1/00	750	000		0.74	151	
			230	50	5.0	350	49	20	1/38	750	260	36	0.80	169	
			220	60	E 0	250	40	00	1/00	000	000	000 01	0.72	157	
			230	60	5.0	350	49	20	1/38	900	220	31	0.76	173	4.0
TP			220	50	1.5	85	12.0	4.5	1/170	750	60	8.5	0.40	54	4.0
		Continuous	230	50	1.0	00	12.0	4.0	1/1/0	100	00	0.0	0.43	60	
		Jonunuous	220	60	1.1	100	14.2	5.5	1/140	900	60	8.5	0.39	49	
			230			100		0.0	1,110	000	00	0.0	0.41	54	

\* The torque setting voltage indicates the value when the external voltage selection switch is set to the "5V" position.

(TP): Contains a built-in thermal protector (automatic return type). If a motor overheats for any reason, the thermal protector is activated and the motor stops.

## How to Read Speed - Torque Characteristics

Torque characteristics are changed when the value set by the internal or external torque potentiometer or external DC voltage is changed. A characteristics example is shown below.



#### 1) Torque Setting Voltage

The set value when a DC power supply of 0 to 5 VDC is used with the external voltage select switch set to the "5V" position.\*

2 Rating: 5 minutes

If the torque setting voltage is 5.0 VDC, the service rating is 5 minutes. The rated time is determined by the maximum permissible temperature of the motor.

#### ③ Rating: Continuous

The range where the motor can be used continuously. The torque setting voltage that permits continuous motor operation varies from one product to another. Check the specific voltage for each product in the specification table.

\* When a DC power supply of 0 to 10 VDC is used by setting the external voltage select switch to the "10V" position, each torque setting voltage becomes twice the corresponding voltage when a DC power supply of 0 to 5 VDC is used.

## Specifications of Power Controller RoHS

Item	Specifications			
Power Supply	Single-Phase 100/110/115 VAC ± 10% 50/60 Hz			
Input	Single-Phase 200/220/230 VAC ± 10% 50/60 Hz			
Power Source for Control	24 VDC ± 10%, 100 mA or more			
	Select one of the following methods:			
Torque	<ul> <li>Set using the internal torque potentiometer (TORQUE)</li> </ul>			
Setting	• Set using the external torque potentiometer : <b>PAVR-20KZ</b> (20 k $\Omega$ , 1/4 W)			
Method	<ul> <li>Set using external DC voltage: 0 to 5 VDC or 0 to 10 VDC, 1 mA or more.</li> </ul>			
	Torque can be adjusted using the torque fine-tuning potentiometer (ADJUST).			
Input Signals	Photocoupler input, Input resistance 4.7 k $\Omega$			
input Signais	CW input, CCW input, INT/EXT switch input, Alarm reset input			
Output	Open collector output: 4.5~26.4 VDC or less, 40 mA or less.			
Signals	Alarm output			
	When any of the following is activated, the alarm signal will be output, the alarm			
Protective	LED will blink, and the motor will stop.			
Function	• The built-in thermal protector of the motor has actuated (become open).			
	<ul> <li>Improper motor cable connection or wire breakage.</li> </ul>			
Motor cable length	The distance between motor and power controller can be extended up to 20 m.			

## General Specifications

Item	Specifications			
Insulation Resistance	100 M $\Omega$ or more when 500 VDC megger is applied between the main circuit terminals and the control circuit terminals after continuous operation under normal ambient temperature and humidity.			
Dielectric Strength	Sufficient to withstand 3.0 kVAC at 50 Hz or 60 Hz applied between the main circuit terminals and the control circuit terminals for 1 minute under normal ambient temperature and humidity.			
Ambient Temperature	$0 \sim +50^{\circ}$ C (+32 $\sim$ +122°F) (non-freezing)			
Ambient Humidity	85% or less (non-condensing)			
Degree of Protection	IP20			

## Safety Standards and CE Marking of Power Controller

Standards	Certification Body	Standards File No.	CE Marking	
UL508	UL	E91291	Low Voltage Directives	
EN 50178	Conform to EN Standards		Low Voltage Directives EMC Directives	
EN 60950-1	Comorni lo E			

• The EMC value changes according to the wiring and layout. Therefore, the final EMC level must be checked with the power controller incorporated in the user's equipment.

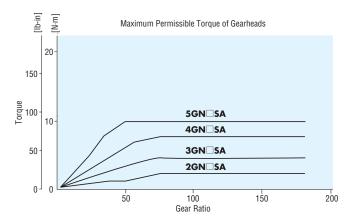
## Output Torque of Gearmotor

Due to the speed - torque characteristics, torque motors can be operated over a wide speed range, from locked rotor condition to the maximum speed. The permissible torque when a gearhead and a decimal gearhead are directly connected can be calculated according to the following formula, using the speed and torque determined from the speed - torque characteristics.

Ī

```
Speed of gearhead output shaftN_G = Motor speed x 1/gearhead gear ratioOutput torque of gearheadT_G = Motor torque x Gearhead gear ratio x Gearhead efficiency
```

The output torque of the gearhead must be lower than the maximum permissible torque.



Gearhead Model	Gearhead Gear Ratio	Gearhead Efficiency
2GN□SA	3~18	81%
3GN□SA 4GN□SA	25~36	73%
5GN SA	50~18 <b>0</b>	66%

Gearheads and decimal gearheads are sold separately.
 Enter the gear ratio in the box ( ) within the model name.

## How to Use as a Brake

A torque motor operates at a speed balanced with the load according to the motor's speed – torque characteristics, when not receiving a force that rotates it in the reverse direction.

If the torque motor is to be used as a brake, rotate the motor in the reverse direction using a torque greater than the motor starting torque. As the torque motor rotates in the reverse direction, it generates a certain level of braking force. Fig. 1 shows an example of speed-brake torque characteristics in an application. In a braking application, a large braking force can be obtained from just above 0 r/min. This feature is suitable for applications where tension must be applied even when the motor is at standstill.

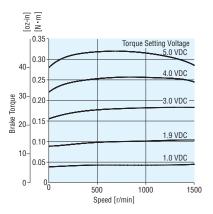


Fig.1 Speed-Brake Torque Characteristics (Example)

## Features of Torque Motor and Application Examples

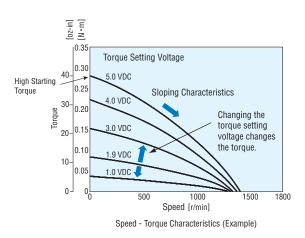
Torque motors have different features than induction motors and reversible motors.

The features specific to torque motors and examples of how these features can be applied are explained.

#### Features of Torque Motor

- Torque can be adjusted by changing the voltage applied to the motor.
- High starting torque and sloping characteristics.
- Usable over the entire range of speed torque characteristics.
- Provides stable torque in a locked state or at low speed.
- Functions as a brake when the motor can be rotated in the reverse direction.
- If the load is constant, the speed can be changed by adjusting the applied voltage.
- If the applied voltage is constant, the speed changes when the load changes.

With the power controller **TMP-1**, the applied voltage, and consequently the torque, can be changed by adjusting the torque setting voltage or each torque potentiometer.

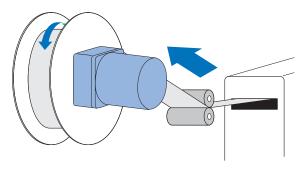


#### • Examples of Torque Motor Application

Shown below are representative examples of utilizing the features of a torque motor.

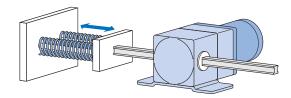
#### ♦Winding

The sloping characteristics of a torque motor are ideal for applications where the work is wound at a constant speed and tension.



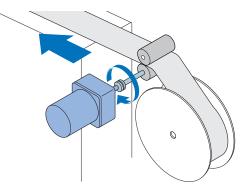
#### ◇Push Motion

Since a torque motor provides stable torque in a locked state or near-locked operation at low speed, it is suitable for push-motion operation.\*



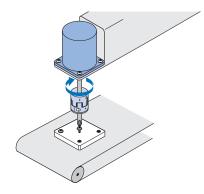
#### 

The braking force of a torque motor can be used to tension the material as it is wound to remove slack.



#### $\bigcirc$ Tightening

Since a torque motor provides stable torque in a locked state or near-locked operation at low speed, it is suitable for applications where screws, etc., are tightened.\*

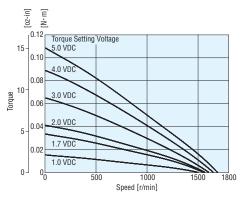


\* The output torque increases when the motor is locked. If a gearhead or linear head is used with a torque motor, do not hit any mechanical stops. The impact generated when the work contacts the mechanical stop may damage the gearhead or linear head.

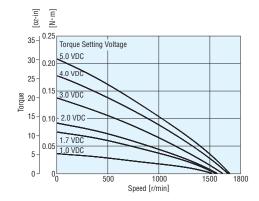
## Speed - Torque Characteristics (Reference Values)

The torque setting voltage indicates the value when the external voltage selection switch is set to the "5V" position. The characteristics are applicable for the motors only.

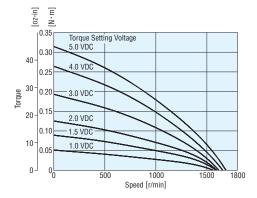
#### 2TK3GN-AW2U, 2TK3A-AW2U (115V 60Hz)



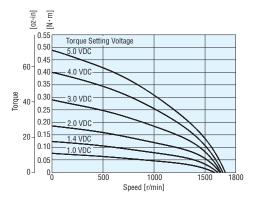
3TK6GN-AW2U, 3TK6A-AW2U (115V 60Hz)



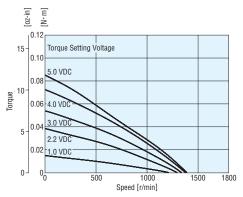
#### 4TK10GN-AW2U, 4TK10A-AW2U (115V 60Hz)



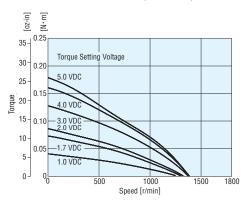
5TK20GN-AW2U, 5TK20A-AW2U (115V 60Hz)



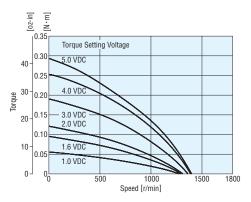
#### 2TK3GN-CW2E, 2TK3A-CW2E (230V 50Hz)



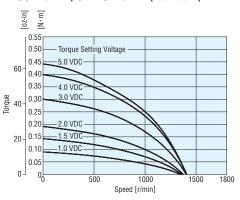
3TK6GN-CW2E, 3TK6A-CW2E (230V 50Hz)



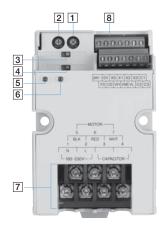
4TK10GN-CW2E, 4TK10A-CW2E (230V 50Hz)



5TK20GN-CW2E, 5TK20A-CW2E (230V 50Hz)



## Name and Function of each Part of the Power Controller



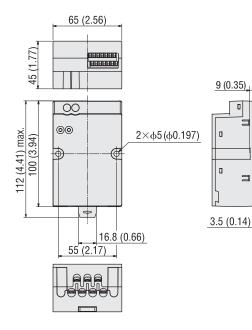
No.	Name	Description
1	Internal torque potentiometer (TORQUE)	Sets the motor torque.
2	Torque fine-tuning potentiometer (ADJUST)	Fine-tunes the variation in the motor torque with respect to the set torque.
3	Sink/source input select switch	Switches between the sink logic and source logic for the input circuit.
4	External voltage select switch	Switches between 5 V and 10 V according to the external DC power supply used when external DC voltage is used to set torque.
5	POWER LED (green)	Lights while the AC power is supplied.
6	ALARM LED (red)	Blinks while an alarm is present. (The alarm output turns OFF.)

#### Imain Circuit Terminals

Terminal No. Terminal Name		Name	Description				
1	N	AC power supply connection terminal	Connects the AC power supply. N: Neutral/L: Live				
2	L	Ac power supply connection terminal					
3	CAPACITOR	Capacitor connection terminal	Connects the capacitor.				
4	GAFAGITUN						
5	BLK		Connects the motor.				
6	RED	Motor connection terminal	BLK: Black/RED: Red/WHT: White				
7	WHT						

## **Dimensions** Unit = mm (inch)

Mass : 0.18kg (0.40 lb.)



#### B Control Circuit Terminals

	Terminal Name	Name	Description			
	24V	+24VDC	Connects the 24 VDC power for control circuit.			
	0V	OV				
	X0	CW input	These inputs control the rotation direction and RUN/STOP mode of the			
	X1	CCW input	motor. If both inputs turn ON simultaneously, the motor stops.			
	X2	INT/EXT switch input	Switches between the internal and external torque settings.			
	X3	Alarm reset input	Resets alarms.			
	C1	IN-COM0	The polarity changes depending on whether the sink or source logic is applied. (Sink: 0 V/Source: 24 V)			
	YO	Alarm output	These terminals output an alarm signal. Once generated, alarms will not be cleared unless reset. (4.5 to 26.4 VDC, 40 mA or less)			
-	CO	OUT-COM				
	VH	VH input	These feedbacks are takened when the standard are			
	VM	VM input	These inputs allow torque to be set using the external torque potentiometer or external DC voltage.			
	VL	VL input				
	C2		If an external power supply is used by applying the source logic, connect			
	C3	IN-COM1	these terminals to the GND line of the external power supply. (Input signal common: 0 V)			

## Accessory (Sold separately)

External Torque Potentiometer

Use this potentiometer if motor torque must be set externally from the power controller.

#### 

 $(20 \text{ k}\Omega, 1/4 \text{ W}, \text{ with a linear resistance vs. angle curve})$ 



This product is manufactured at a plant certified with the international standards **ISO 9001** (for quality assurance) and **ISO 14001** (for systems of environmental management).

Specifications are subject to change without notice. This catalog was published in May, 2008.

## **ORIENTAL MOTOR U.S.A. CORP.**

Western Sales and Customer Service Center Tel: (310) 715-3301 Fax: (310) 225-2594

Los Angeles

Tel: (310) 715-3301

San Jose Tel: (408) 392-9735

#### **Technical Support**

Tel: (800) 468-3982 / 8:30 a.m. to 5:00 p.m., P.S.T. (M–F) 7:30 a.m. to 5:00 p.m., C.S.T. (M–F) E-mail: techsupport@orientalmotor.com Copyright ©2008 ORIENTAL MOTOR U.S.A. CORP.

 
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